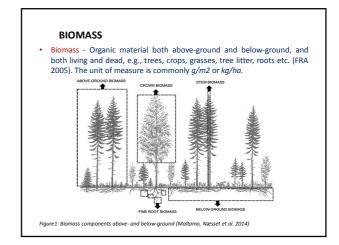
Remote Sensing of Tree Structure and Biomass in north Australian mesic savannah

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WHY ESTIMATION OF BIOMASS IS IMPORTANT?

- Forest resource management:
 ✓ forest inventory
 - ✓ estimation of timber volume
 - ✓ Forest dynamics and conservation
- As an energy and bioenergy source
- Critical component of tracking carbon and greenhouse gases cycling

 ✓ (above ground biomass (AGB) is approximately 48% carbon)
- Forest fire management:
 ✓ Forest fuel and their vertical structure distribution

BIOMASS ESTIMATION APPROACHES

- In general, biomass can be measured via three primary methods:
 - a) destructive measurement by field work;
 - b) non-destructive estimates using allometric equations or conversion;
 - c) by using remote sensing

Allometry assumes that a relationship exists, by species, based on size or amount of tree size (e.g. diameter at breast height (DBH), top height, and crown area) to the dry weight of the above and/or below ground components of biomass

(typical allometric model - single-tree diameter/height)

MEASUREMENT OF FOREST BIOMASS

TWO MAIN APPROACHES

Single tree approach, relying on individual tree detection

tree metrics used:

Tree species (wood density); diameter at breast height; Height

 Area-based approach, based on statistical canopy height distribution

tree metrics used:

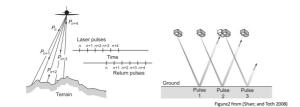
Tree species; tree basal area (m2); Total basal area (m2/ha) (canopy height, crown area, or geometric canopy volume as independent variables)

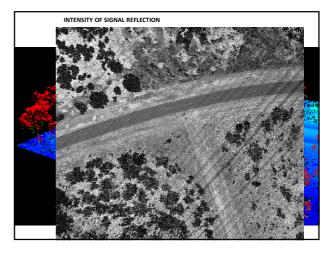
REMOTE SENSING AND BIOMASS ESTIMATION

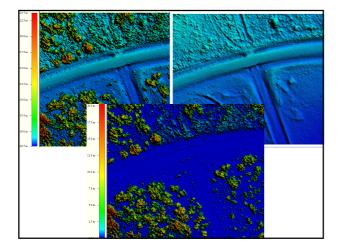
- Biomass cannot be directly measured by remote sensing sensors
- An indicator is the canopy/tree height, based on the close association between tree height and wood volume
- Canopy height models (CHM) provide accurate estimates of forest parameters such as canopy heights, stand volume, and the vertical structure . CHM is result of subtraction of bare ground values (Digital Terrain Model (DTM)) from the canopy layer (Digital Surface Model (DSM)).
- Most accurate height estimations and 3D structure of vegetation could be obtained using Light Detection And Ranging (LiDAR) systems

LIDAR principle

- LiDAR measure the range (i.e., distance) from the sensor to a target, determined by timing the round-trip travel time of a pulse of laser light reflected from a surface. Travel time is converted to distance using the speed of light.
- Position of reflected point calculated by combining distance with knowledge of the position of the sensor in a coordinate frame (GPS+IMU) and a vector that defines the location of the reflecting target.







LASER SCANNING IN FORESTRY USE

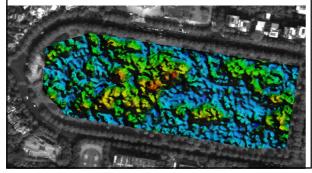
Parameters and forest inventory attributes extracted by LiDAR:

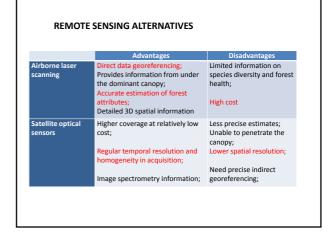
- Tree HeightsDTM
- Average Elevation, slope and aspect of relief
- DSM
- CHM Canopy Height Model
- Tree Peak identification (finding local maxima in CHM)
- Canopy Projection Area (CPA) result of segmentation
- Centroid of the CPA
- Local tree density number of trees per unit area
- Canopy volumeCanopy base Height (CBH)



REMOTE SENSING ALTERNATIVES

 By using the high-performance image-matching technique, the canopy height information can be easily and automatically extracted from satellite and aerial images in stereo and multi-image mode.







 Precisely exchanging data between scales is essential as many environmental and resource management problems can only be dealt with effectively at broad scales (Wu & Qi, 2000).

